
Lay Chapter 5, Eigenvalues and Eigenvectors

Eigenvalues and Eigenvectors

Mathematica has several commands for working with eigenvalues and eigenvectors.

```
Clear[a]
```

$$\mathbf{a} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix};$$

```
eigenvals = Eigenvalues[a]
```

```
{6, 0, 0}
```

Since the Eigenvectors command returns a list eigenvectors, those eigenvectors will appear as rows of a matrix. It is frequently convenient to reassemble them as columns of a matrix.

```
eigenvecsRows = Eigenvectors[a];  
% // MatrixForm
```

```
eigenvecs = Transpose[eigenvecsRows];  
% // MatrixForm
```

$$\begin{pmatrix} 1 & 1 & 1 \\ -3 & 0 & 1 \\ -2 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -3 & -2 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

The Eigensystem command returns both eigenvalues and eigenvectors.

```
Eigensystem[a];
Map[MatrixForm, %]
```

$$\left\{ \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 & 1 \\ -3 & 0 & 1 \\ -2 & 1 & 0 \end{pmatrix} \right\}$$

Diagonalization of a matrix, $A = P^{-1} \cdot \Lambda \cdot P$

An important result from linear algebra takes the form

```
(* P.A.P-1 == Λ and A == P-1.Λ.P *)
```

when the matrix A is diagonalizable. Let's work towards that result.

```
diagλ = DiagonalMatrix[eigenvals];
% // MatrixForm
```

$$\begin{pmatrix} 6 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Now, observe.

```
a.eigenvecs;
% // MatrixForm
```

$$\begin{pmatrix} 6 & 0 & 0 \\ 6 & 0 & 0 \\ 6 & 0 & 0 \end{pmatrix}$$

```
eigenvecs.diagλ;
% // MatrixForm
```

$$\begin{pmatrix} 6 & 0 & 0 \\ 6 & 0 & 0 \\ 6 & 0 & 0 \end{pmatrix}$$

Therefore,

```
Inverse[eigenvecs].a.eigenvecs;
% // MatrixForm

diagλ == Inverse[eigenvecs].a.eigenvecs


$$\begin{pmatrix} 6 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```

```
True
```

and

```
eigenvecs.diagλ.Inverse[eigenvecs];
% // MatrixForm

a == eigenvecs.diagλ.Inverse[eigenvecs]


$$\begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix}$$

```

```
True
```

Another Matrix Diagonalization, $A == P^{-1} \cdot \Lambda \cdot P$

```
Clear[a]

a = 
$$\begin{pmatrix} -6 & 4 & 0 & 9 \\ -3 & 0 & 1 & 6 \\ -1 & -2 & 1 & 0 \\ -4 & 4 & 0 & 7 \end{pmatrix};$$

```

```
eigenvals = Eigenvalues[a]
```

```
{5, -2, -2, 1}
```

```
eigenvecsRows = Eigenvectors[a];
% // MatrixForm
```

```
eigenvecs = Transpose[eigenvecsRows];
% // MatrixForm
```

$$\begin{pmatrix} 2 & 1 & -1 & 2 \\ 6 & -3 & 0 & 4 \\ 1 & 1 & 1 & 0 \\ 2 & -1 & -7 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 6 & 1 & 2 \\ 1 & -3 & 1 & -1 \\ -1 & 0 & 1 & -7 \\ 2 & 4 & 0 & 2 \end{pmatrix}$$

```
Eigensystem[a];
Map[MatrixForm, %]
```

$$\left\{ \begin{pmatrix} 5 \\ -2 \\ -2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 & 1 & -1 & 2 \\ 6 & -3 & 0 & 4 \\ 1 & 1 & 1 & 0 \\ 2 & -1 & -7 & 2 \end{pmatrix} \right\}$$

```
diagλ = DiagonalMatrix[eigenvals];
% // MatrixForm
```

$$\begin{pmatrix} 5 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Now, observe.

```
a.eigenvecs;  
% // MatrixForm
```

$$\begin{pmatrix} 10 & -12 & -2 & 2 \\ 5 & 6 & -2 & -1 \\ -5 & 0 & -2 & -7 \\ 10 & -8 & 0 & 2 \end{pmatrix}$$

```
eigenvecs.diagλ;  
% // MatrixForm
```

$$\begin{pmatrix} 10 & -12 & -2 & 2 \\ 5 & 6 & -2 & -1 \\ -5 & 0 & -2 & -7 \\ 10 & -8 & 0 & 2 \end{pmatrix}$$

Therefore,

```
Inverse[eigenvecs].a.eigenvecs;  
% // MatrixForm
```

```
diagλ == Inverse[eigenvecs].a.eigenvecs
```

$$\begin{pmatrix} 5 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

```
True
```

and

```
eigenvecs.diagλ.Inverse[eigenvecs];
% // MatrixForm

a == eigenvecs.diagλ.Inverse[eigenvecs]


$$\begin{pmatrix} -6 & 4 & 0 & 9 \\ -3 & 0 & 1 & 6 \\ -1 & -2 & 1 & 0 \\ -4 & 4 & 0 & 7 \end{pmatrix}$$

```

```
True
```

Characteristic Polynomial

Calculate the characteristic polynomial of a certain square matrix.

```
Clear[a, λ, id]

a =  $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ ;
id = IdentityMatrix[2];

ch[λ_] = Det[a - λ id]

-2 - 5 λ + λ2
```

Roots of $ch[\lambda]$ are eigenvalues of a .

```
Solve[ch[λ] == 0, λ] // Flatten

 $\left\{ \lambda \rightarrow \frac{1}{2} (5 - \sqrt{33}), \lambda \rightarrow \frac{1}{2} (5 + \sqrt{33}) \right\}$ 
```

Complex Eigenvalues

```
Clear[a]
```

```
a =  $\begin{pmatrix} 1 & -2 \\ 1 & 3 \end{pmatrix}$ ;
```

```
eigenvals = Eigenvalues[a]
```

```
{2 + i, 2 - i}
```

```
eigenvecsRows = Eigenvectors[a];
```

```
% // MatrixForm
```

```
eigenvecs = Transpose[eigenvecsRows];
```

```
% // MatrixForm
```

```
 $\begin{pmatrix} -1 + i & 1 \\ -1 - i & 1 \end{pmatrix}$ 
```

```
 $\begin{pmatrix} -1 + i & -1 - i \\ 1 & 1 \end{pmatrix}$ 
```

```
Eigensystem[a];
```

```
Map[MatrixForm, %]
```

```
 $\left\{ \begin{pmatrix} 2 + i \\ 2 - i \end{pmatrix}, \begin{pmatrix} -1 + i & 1 \\ -1 - i & 1 \end{pmatrix} \right\}$ 
```

```
diagλ = DiagonalMatrix[eigenvals];
```

```
% // MatrixForm
```

```
 $\begin{pmatrix} 2 + i & 0 \\ 0 & 2 - i \end{pmatrix}$ 
```

Now, observe.

```
a.eigenvecs;  
% // MatrixForm  
  

$$\begin{pmatrix} -3 + i & -3 - i \\ 2 + i & 2 - i \end{pmatrix}$$

```

```
eigenvecs.diagλ;  
% // MatrixForm  
  

$$\begin{pmatrix} -3 + i & -3 - i \\ 2 + i & 2 - i \end{pmatrix}$$

```

Therefore,

```
Inverse[eigenvecs].a.eigenvecs;  
% // MatrixForm  
  
diagλ == Inverse[eigenvecs].a.eigenvecs  
  

$$\begin{pmatrix} 2 + i & 0 \\ 0 & 2 - i \end{pmatrix}$$

```

```
True
```

and

```
eigenvecs.diagλ.Inverse[eigenvecs];  
% // MatrixForm  
  
a == eigenvecs.diagλ.Inverse[eigenvecs]  
  

$$\begin{pmatrix} 1 & -2 \\ 1 & 3 \end{pmatrix}$$

```

```
True
```

Polar Form of a Matrix

```
Clear[m, a, b, φ, rot, r]
```

```
a =  $\sqrt{3}$ ;
```

```
b = 1;
```

```
m =  $\begin{pmatrix} a & -b \\ b & a \end{pmatrix}$ ;
```

```
% // MatrixForm
```

```
 $\begin{pmatrix} \sqrt{3} & -1 \\ 1 & \sqrt{3} \end{pmatrix}$ 
```

Find the angle of the rotation.

```
φ = ArcTan[b / a]
```

```
 $\frac{\pi}{6}$ 
```

... and compute the rotation matrix.

```
rot[φ_] :=  $\begin{pmatrix} \text{Cos}[\varphi] & -\text{Sin}[\varphi] \\ \text{Sin}[\varphi] & \text{Cos}[\varphi] \end{pmatrix}$ ;
```

```
rot[φ];
```

```
% // MatrixForm
```

```
 $\begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix}$ 
```

Find the scaling factor.

```
r =  $\sqrt{a^2 + b^2}$ 
```

```
2
```

Check the decomposition.

```
m == r rot[φ]

True
```

The Rotation Due to a Complex Eigenvalue

If a real 2x2 matrix has a complex eigenvalue, a particular decomposition will display the rotation "hidden within."
See Lay 5.5, pp. 338--341.

```
Clear[m, a, b, c, p];

m =  $\begin{pmatrix} 1 & -2 \\ 1 & 3 \end{pmatrix}$ ;
% // MatrixForm

 $\begin{pmatrix} 1 & -2 \\ 1 & 3 \end{pmatrix}$ 
```

```
evals = Eigenvalues[m]

{2 + i, 2 - i}
```

Construct the matrix c.

```
a = Re[evals[[1]]];
b = -Im[evals[[1]]];

c =  $\begin{pmatrix} a & -b \\ b & a \end{pmatrix}$ ;
% // MatrixForm

 $\begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix}$ 
```

Construct the matrix p.

```
vecs = Eigenvectors [m]  
  
{{-1 + i, 1}, {-1 - i, 1}}
```

```
p1 = Re[vecs[[1]]];  
p2 = Im[vecs[[1]]];  
  
p = Transpose[{p1, p2}];  
% // MatrixForm  
  

$$\begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix}$$

```

Check these results.

We should find that $m = p.c.Inverse[p]$ where c is a polar matrix (rotation with scaling).

```
p.c.Inverse [p];  
% // MatrixForm  
  
m == p.c.Inverse [p]  
  

$$\begin{pmatrix} 1 & -2 \\ 1 & 3 \end{pmatrix}$$

```

```
True
```